2 Specifications

## 2-3-2 Multi axis drive unit

## (1) 3-axis integrated servo drive unit

		3-axis integrated servo drive unit MDS-DM-V3 Series					
Servo drive unit type MDS-DM-V3-		202020	404040				
Nominal maximum current (peak) [A]		20/20/20	40/40/40				
Output	Rated voltage [V]	AC155					
	Rated current [A]	6.4/6.4/6.4 11/11/11					
Input	Rated voltage [V]	DC270 to 311					
	Rated current [A]	21	21				
Control power	Voltage [V]	200AC (50Hz) / 200 to 230AC (60Hz) Tolerable fluctuation between +10% and -15%					
	Frequency [Hz]	50/60 Tolerable fluctuation between +3% and -3%					
	Maximum current [A]	0.2					
	Maximum rush current [A]	30					
	Maximum rush conductivity time [ms]	6					
Earth leakage current [mA]		1 (Max. 2)					
Control method		Sine wave PWM control method					
Proking		Regenerative braking and dynamic brakes					
Braking	Dynamic brakes	Built-in					
External analog output		0 to +5V, 2ch (data for various adjustments)					
Degree of protection		IP20 [over all]					
Cooling method		Forced air cooling					
Mass [kg]		3.8					
Heat radiated at rated output [W]		89	159				
Noise		Less than 55dB					
Unit outline dimension drawing		A0					

## (2) Multi axis integrated drive unit

		Multi axis integrated drive unit MDS-DM-SPV2/SPV3 Series								
Drive unit type MDS-DM-		SPV2F-				SPV3F-				
		10080	16080	20080	10080	16080	20080	200120		
Nominal maximum current (at peak of spindle section) [A]		100	160	200	100	160	200	200		
Nominal maximum current (at peak of servo section) [A]		80×2				80×3				
Power facility capacity [kVA]		17.1	21.7	27.0	28.2	14.7	19.3	24.6		
	Rated voltage [V]	AC155								
Output	Rated current (spindle axis) [A]	26	37	67	26	37	67	67		
	Rated current (servo) [A]	15.8×2				15.8×3				
Input	Rated voltage [V]	AC200 (50Hz) /AC200 to 230 (60Hz) Tolerable fluctuation between +10%				een +10% and	-15%			
	Rated current [A]	33	43	55	38	48	60	65		
	Voltage [V]	DC24±10%								
Control power	Maximum current [A]	4.0								
	Maximum rush current [A]	10								
	Maximum rush conductivity time [ms]	100								
Earth leakage current [mA]		9/ Max.21 (Details: Spindle 6/Max.15, Servo per one axis 1/Max.2)								
Control method		Sine wave PWM control method								
Ducking		Regenerative braking and dynamic brakes (only regenerative braking for spindle)								
Braking	Dynamic brakes	Built-in								
External analog output		0 to +5V,2ch (data for various adjustments)								
Degree of protection		IP20 [over all] (IP00 [Terminal block TE1])								
Cooling method		Forced air cooling								
Mass [kg]		14.5 15								
Heat radiated at rated output [W]		630	700	895	730	800	990	1260		
Noise		Less than 55dB								
Unit outline dimension drawing					F0					



For outline dimension drawings, refer to "DRIVE SYSTEM DATA BOOK" (IB-1500273(ENG)).